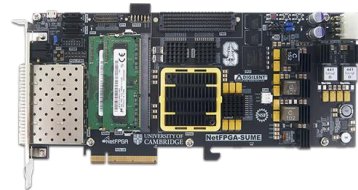
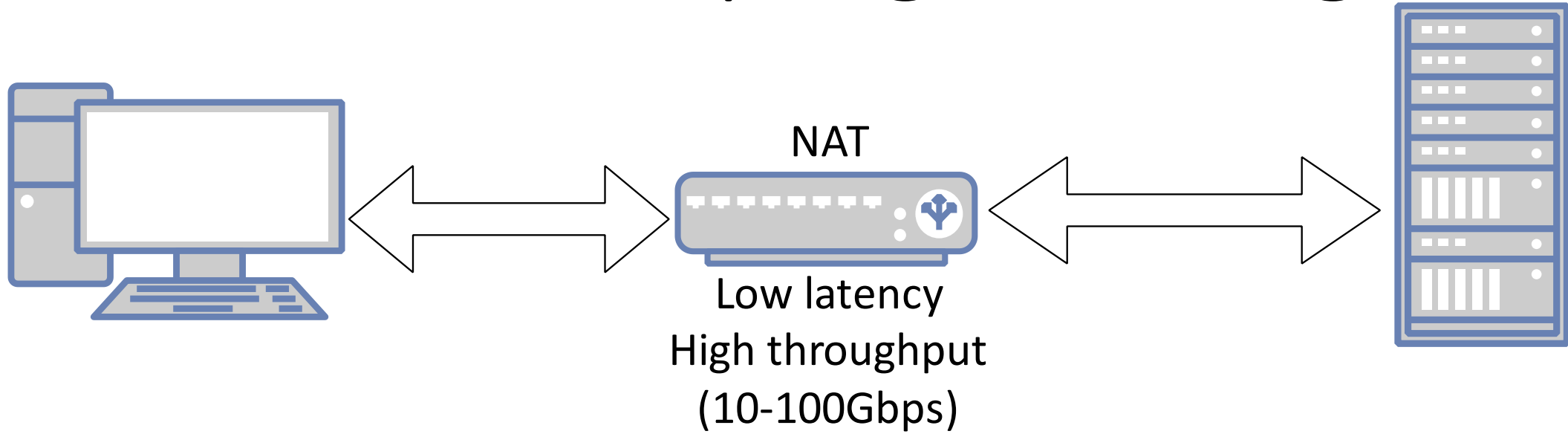


# Using C# for high performance network programming



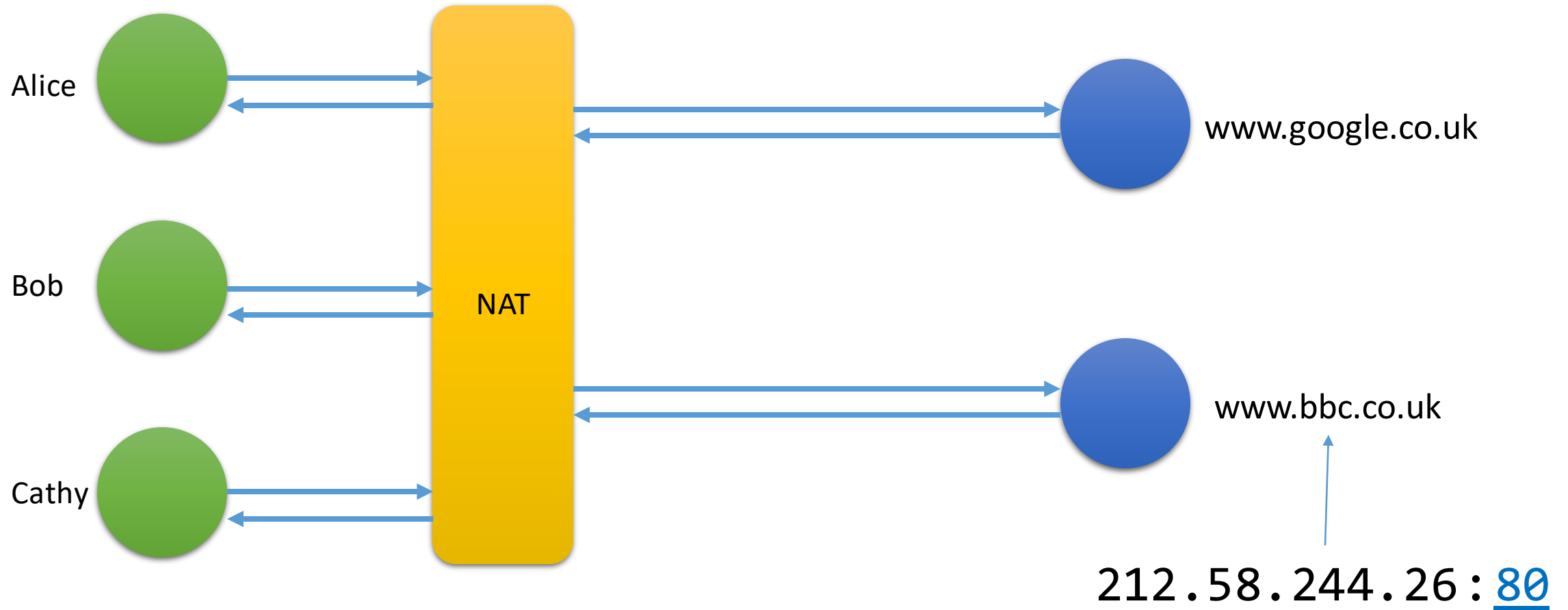
Jonny Shipton

CL, University of Cambridge

# What is a NAT?



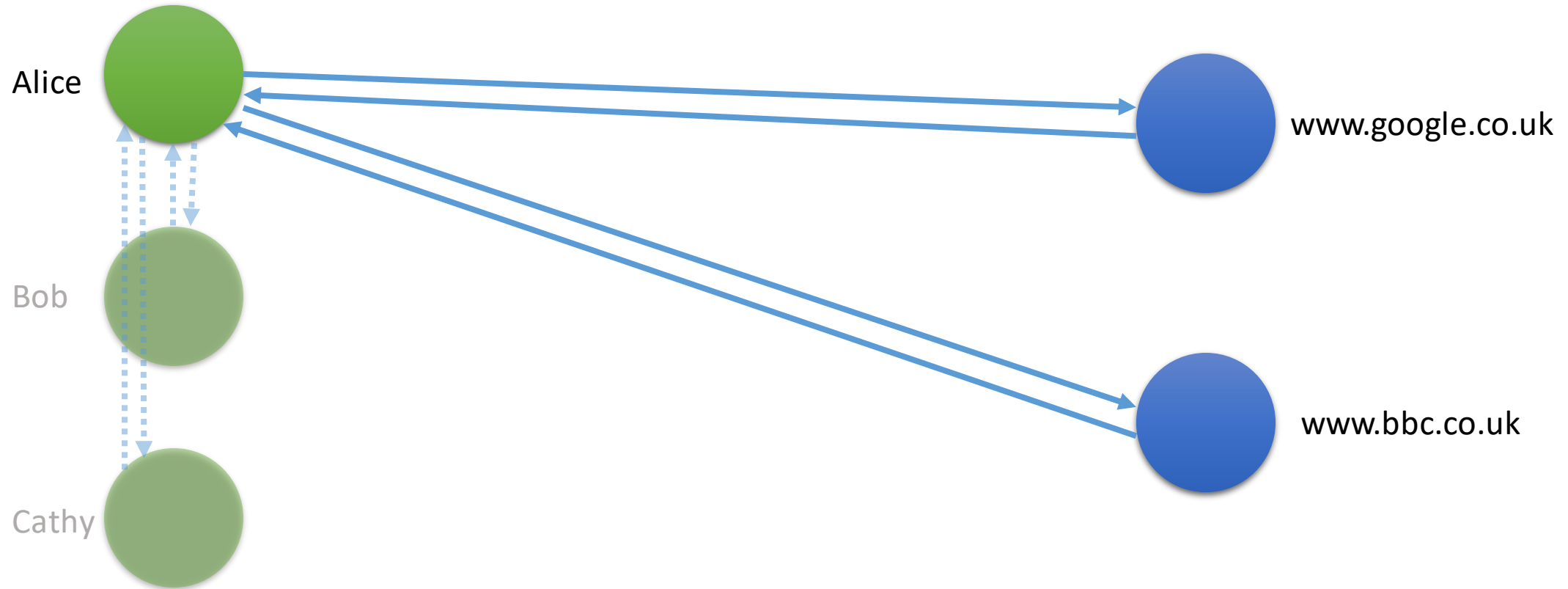
Reality



# What is a NAT?



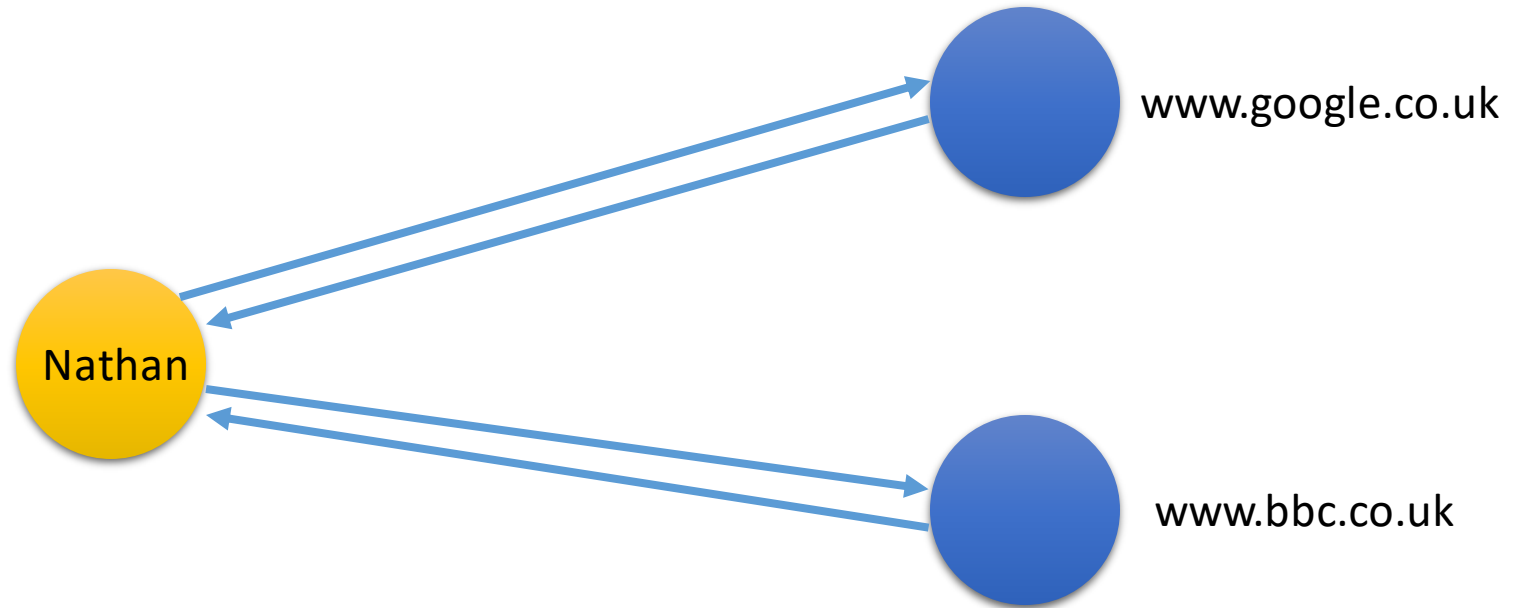
Client's POV



# What is a NAT?

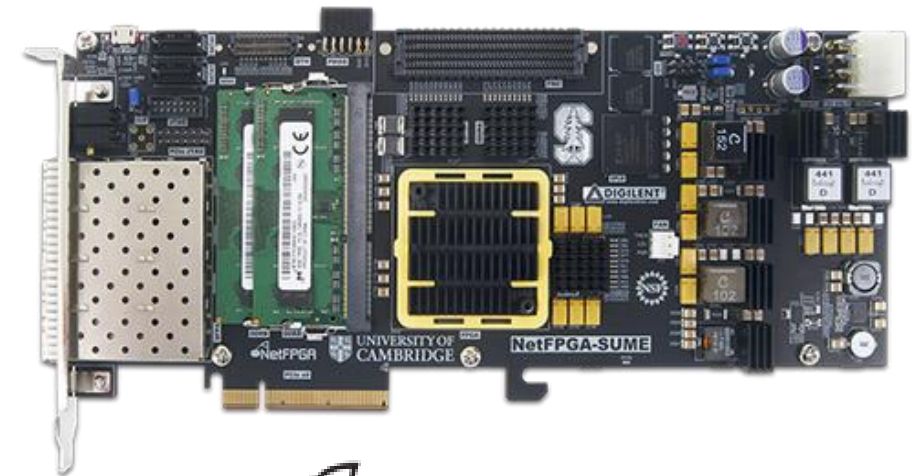


Server's POV

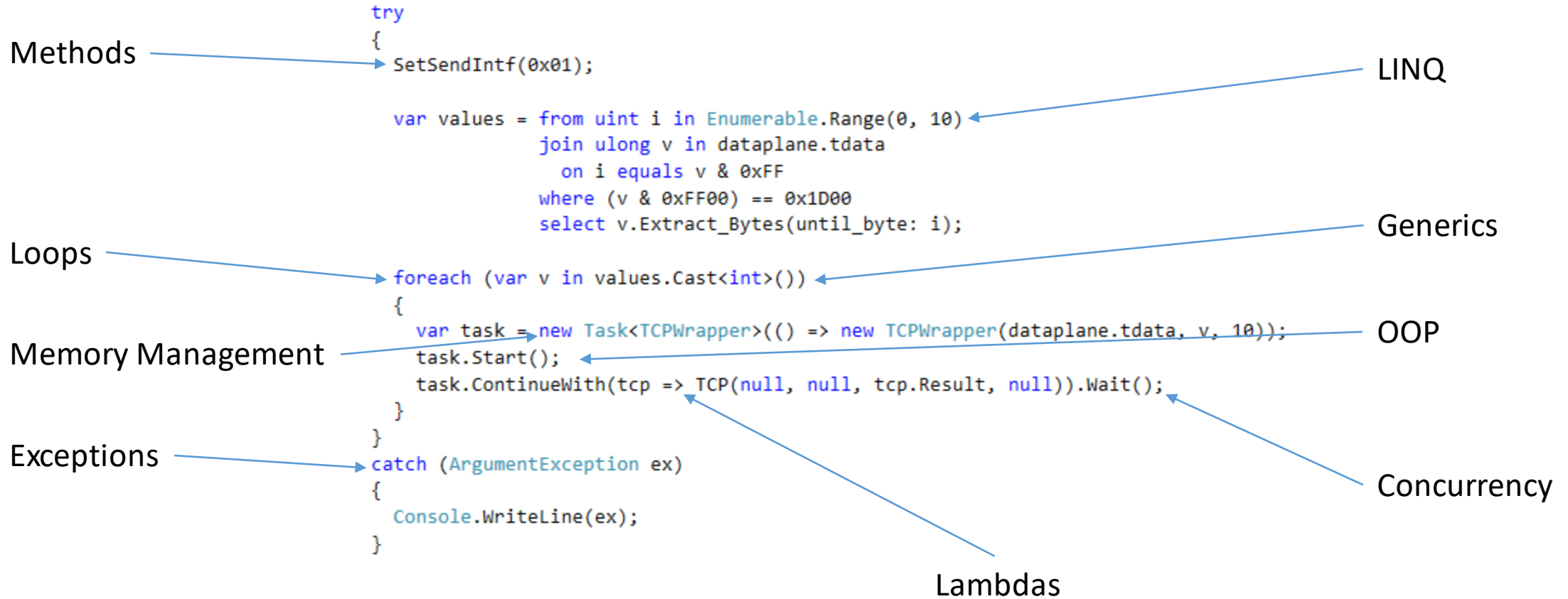


# Why C#?

	Verilog	C#
Performance	✓✓✓	✓
Scalable to 100Gbps+	✓✓✓	✓
Skill base	Small	Large
Comfy language features	☹	✓✓✓

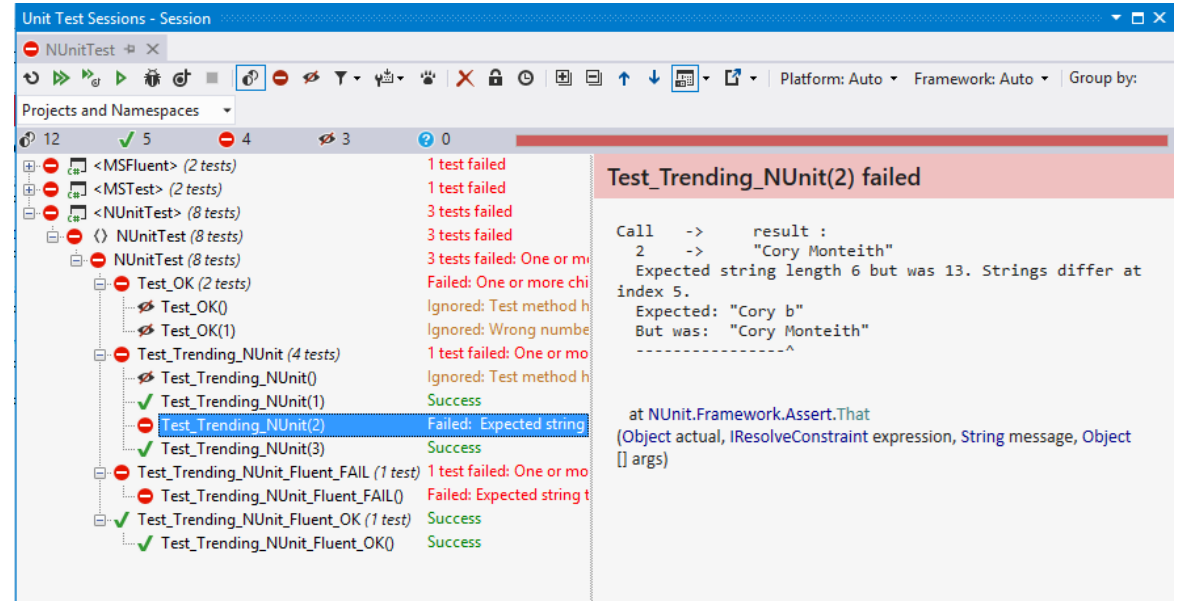
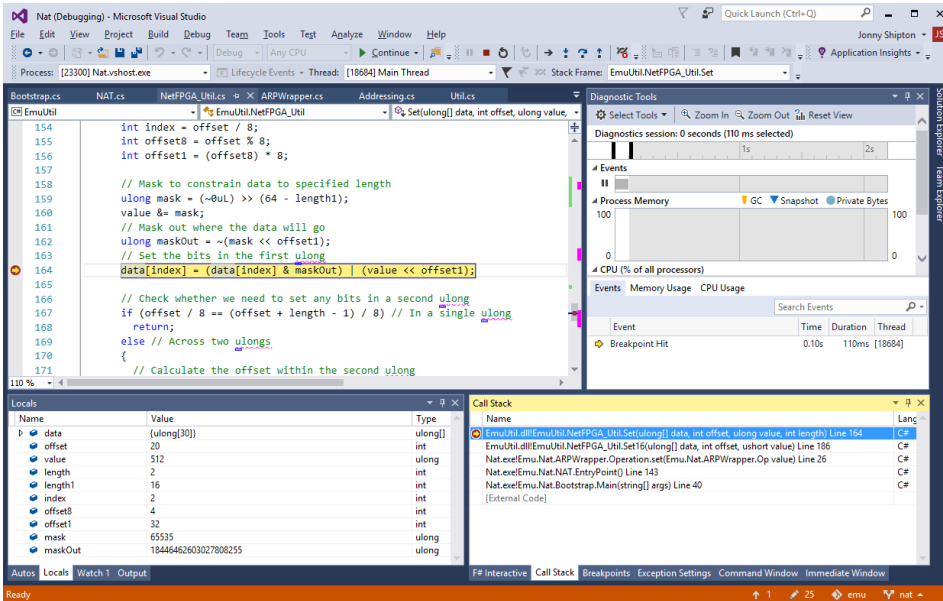


# Why C#?

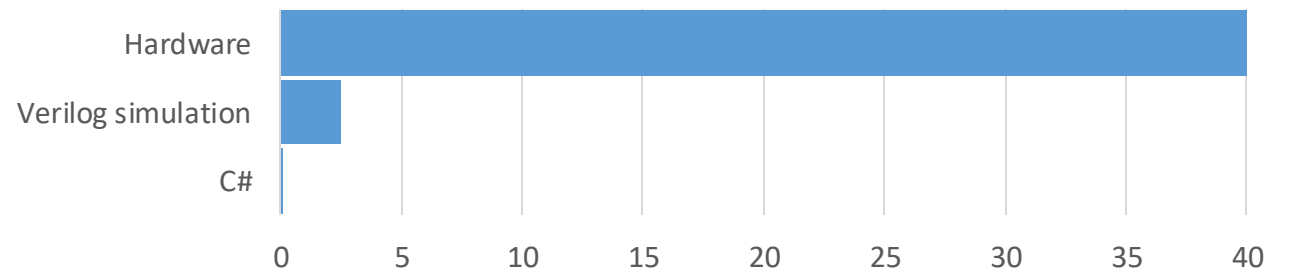


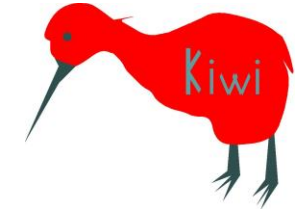
Also iterators, properties, inheritance, libraries, dynamic variables, safe expressive type system, ...

# Why C#?

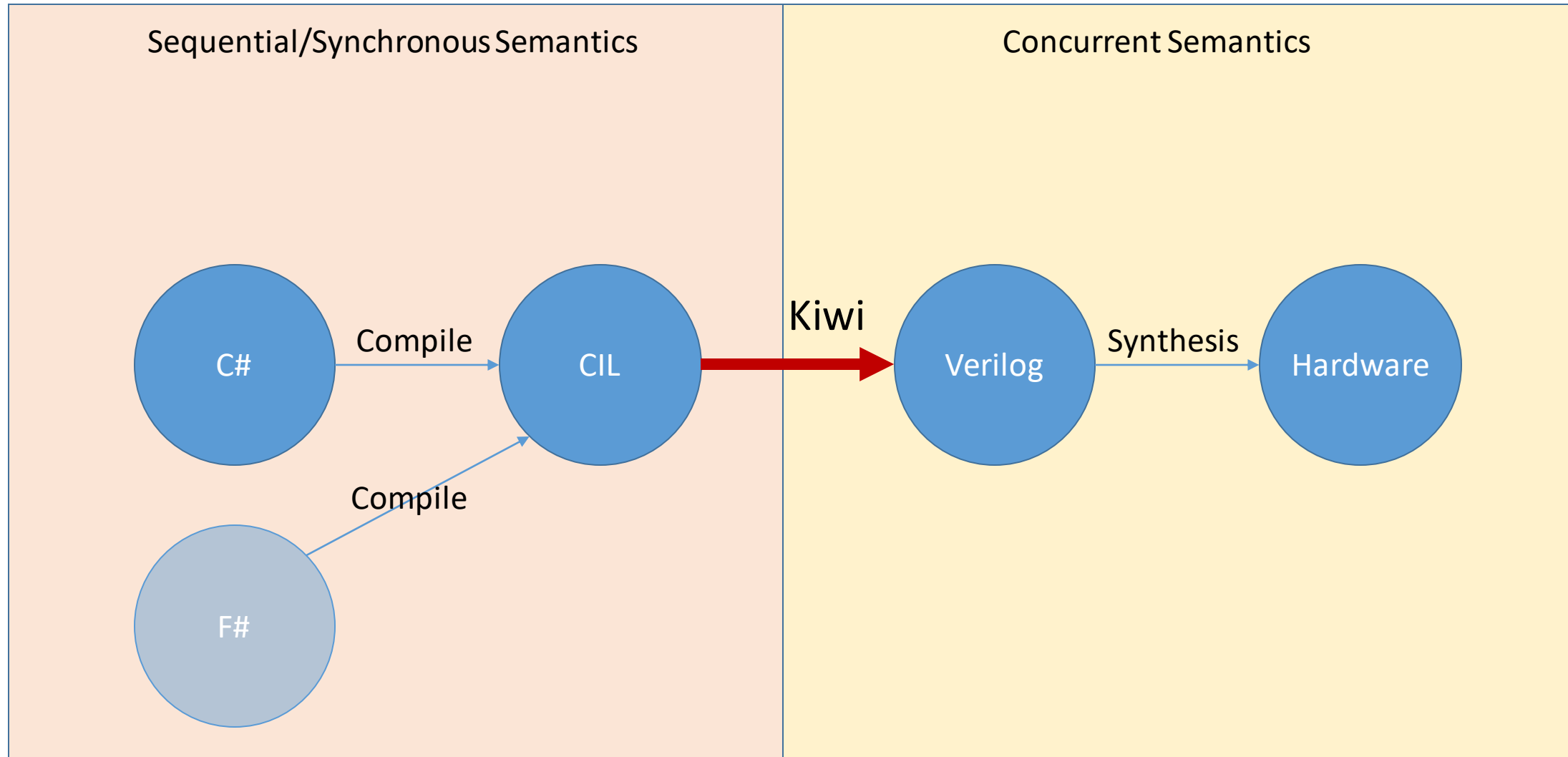


Time (mins) to compile and run





# Compile C# to Verilog?!





# Look at the code

```
else if (eth.EtherType == EthernetWrapper.EtherType.ARP)
{
    if (arp.Operation == ARPWrapper.Op.Request
        && arp.HardwareType == ARPWrapper.HwType.Ethernet
        && arp.ProtocolType == (ushort)EthernetWrapper.EtherType.Ipv4
        && arp.HardwareAddressLength == 6
        && arp.ProtocolAddressLength == 4)
    {
        Kiwi.Pause(); // Reduces Kiwi compile time
        if (arp.TargetProtocolAddress == myInsideIP || arp.TargetProtocolAddress == myOutsideIP) // Request for a MAC I own
        {
            uint intfIp = arp.TargetProtocolAddress;
            ulong intfMac = macOfIntf(dataplane.GetReceiveIntf());

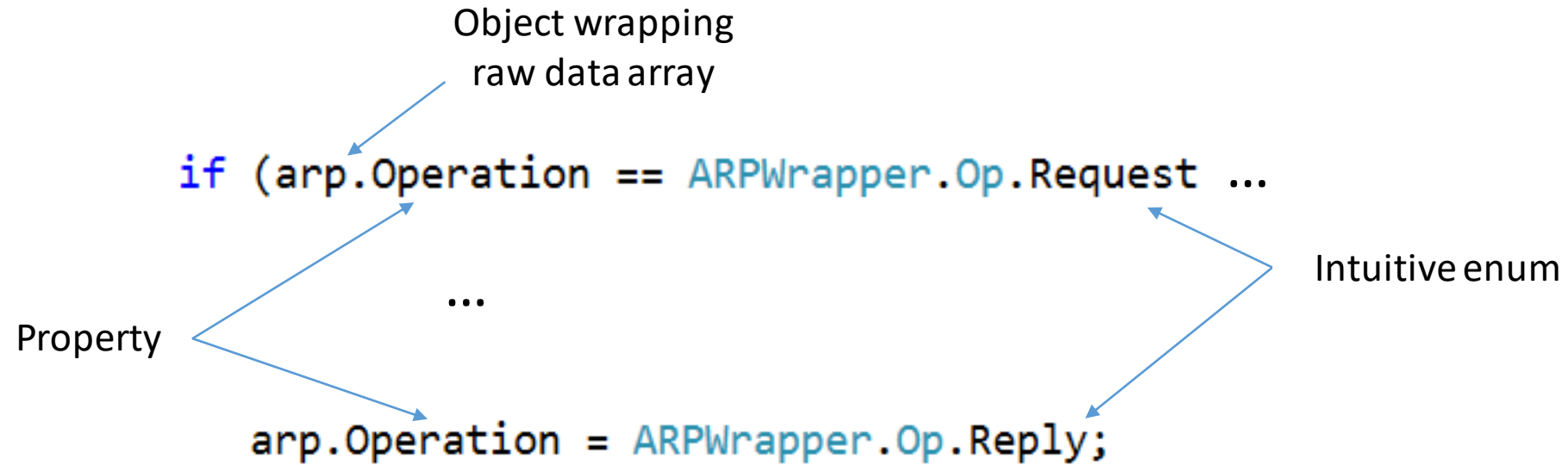
            // Update arp packet to use as response
            arp.Operation = ARPWrapper.Op.Reply;
            arp.TargetHardwareAddress = arp.SenderHardwareAddress;
            arp.TargetProtocolAddress = arp.SenderProtocolAddress;
            arp.SenderHardwareAddress = intfMac;
            arp.SenderProtocolAddress = intfIp;

            // Update ethernet fields
            eth.DestinationMac = arp.TargetHardwareAddress;
            eth.SourceMac = intfMac;

            Kiwi.Pause();

            // Send reply
            SetSendIntf(dataplane.GetReceiveIntf());
            SendFrame(pkt_size);
        }
    }
}
```

# Look at the code



```
public Op Operation { get { return (Op)data.Get16(Offset + 6); }  
                    set { data.Set16(Offset + 6, (ushort)value); } }
```

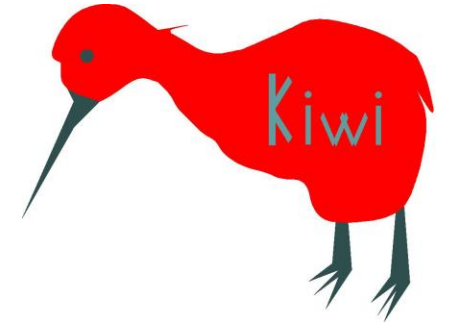
# Limitations

- No truly dynamic allocation (yet)
  - Array sizes must be determined statically
  - Objects can be allocated and used within loops
- Library support less mature
- Complexity -> longer compile times
- No reflection, dynamic invoke, etc.
- Clock cycles are more precious, so we want to do more in each one
  - Asynchronous – Kiwi flattens code

# Thanks to:

- Nik Sultana
- Salvator Galea
- David Greaves
- Networks-as-a-Service  
(Naas-project.org)
- EPSRC
- Kynesim

## Kiwi



## Google “Kiwi compiler”

<http://www.cl.cam.ac.uk/~djg11/kiwi/>

<http://www.cl.cam.ac.uk/research/srg/han/hprls/orangepath/kiwic.html>



## NetFPGA-SUME

<http://netfpga.org/site/#/systems/1netfpga-sume/details/>